Characteristics

- Motor for Clorius valves types L2FM, M2FM, G2FM, L3FM, M3FM and G3FM.
- MT90 is approved for marine applications by Germanischer Loyd, No. 57067-91 HH
- Can be manually operated in case of power failure.
- · Low or high voltage operation
- Digital or analogue version.

Application

Valve motor type MT Marine is specially designed to meet the demands of the powerful low frequency vibration environments in marine installations.

The main applications are cooling of freshwater - sea water - and oil-systems for main and auxiliary engines.

Mounting

For mounting and starting up, the instructions delivered with the motor must be followed carefully. The wiring diagram is fixed inside the motor cover. Valve and motor must be mounted with vertical stems. Free height above/below the motor has to be at least 175 mm for service.

Service

No special service is necessary. It is recommended to check and grease the valve motor at every docking or every three year.

Valve opening

The valve opening can be seen on one of the stays.

Positional potentiometer (option)

The positional potentiometer is adjusted to a 45 mm valve stroke. If using valves with a stroke less than 45 mm, the signal will be reduced according to the table below.

Valve size DN Resistance range in %

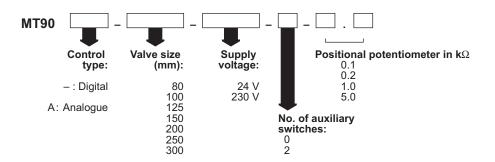
300 mm	0-100 %
300/250 mm	0-100 %
200 mm	0-100 %
150 mm	0-100 %
125 mm	0-100 %
100 mm	81 %
80 mm	69 %



Technical data

Power supply	24 V AC, 50/60 Hz
	or 230 V, 50/60 Hz
Consumption	6.7 W
Closing force	1200 N
Spindle speed	25 mm/min.
Casing	IP65
Ambient temp.	-20 to +60°C
Humidity	0-100% R.H
Manual operation	included
Weight	7.5 kg
Analogue version	0 (2) – 10 V
	or 0 (4) – 20 mA
Positional potention	meter max. 1.5 W
	max. 30 mA
Auxiliary switches	max. 250 V
	max. 5 A (Ohm)
	max. 3 A (inductive)
	max. 1 A (bulb)

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Web: www.cloriuscontrols.com

2-way valves

Max. differential pressure $\,\Delta p_{\!_{L}}$ in bar against which the actuator is able to close.

As a principal rule Δp_L is calculated as inlet pressure $p_1 = \Delta p_L$ (For most valves Δp_L is reduced by an increasing p_1 .)

Valve type →		M2FM, G2FM							L2FM			
Pressure stage → PN 10 (PN 16)						PN 6 (PI	N 10)	PN 10	PN 6			
Application	Motor	Valve motor	Dimension of valve in mm									
		placed	80	100	125	150	200	300/250	300	200	300/250	300
A (2) AB (1)	closes against	below	10	10	10	10	10	5.1	5.1	10	5.1	5.1
	port A(2)	above	10	10	10	10	10	6	6	10	6	6

3-way valves

Max. differential pressure $\,\Delta p_{_{\!L}}$ in bar against which the actuator is able to close.

As a principal rule Δp_{L} is calculated as inlet pressure $p_{1} = \Delta p_{L}$ (For most valves Δp_{L} is reduced by an increasing p_{1} .)

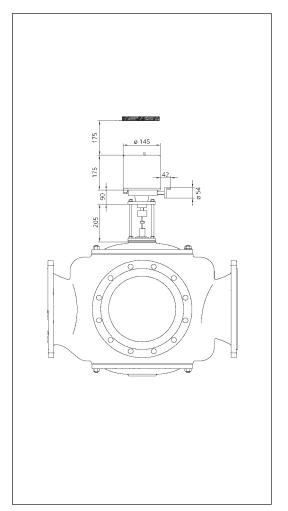
Valve type →	ightarrow M3FM (G3FM)							L3FM					
Pressure stage →				PN 10 (PN 16) PN 6 (PN 10)					N 10)	PN 10	PN 10 PN 6		
Application	Motor	Valve motor placed	Dimension of valve in mm										
			80	100	125	150	200	300/250	300	200	300/250	300	
A (2) AB (1) closes ag	closes against port A(2)	below	10	10	10	10	10	5.1	5.1	10	5.1	5.1	
		above	10	10	10	10	10	6	6	10	6	6	
	closes against	below	10	10	7.4	5.2	7.2	2.8	2.8	7.2	2.8	2.8	
	port B(3)	above	10	9.6	6.9	4.6	6.4	1.6	1.8	6.4	1.6	1.8	
Diverting valve	opens from port B(3)	below	10	10	10	10	10	5.6	5.6	10	5.6	5.6	
A (2) AB (1)		above	10	10	10	10	10	6	6	10	6	6	
	opens from port A(2)	below	10	10	8.1	6	8	3.2	3.2	8	3.2	3.2	
B (3)		above	10	10	7.6	5.3	7.1	2.1	2.3	7.1	2.1	2.3	

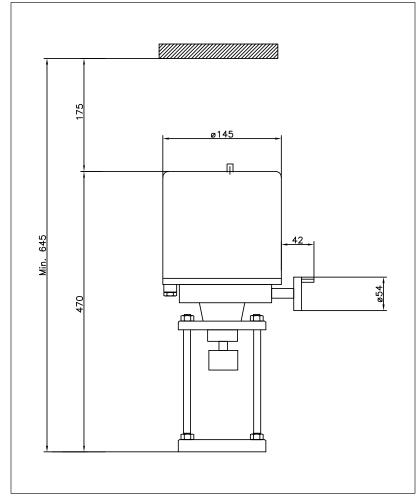
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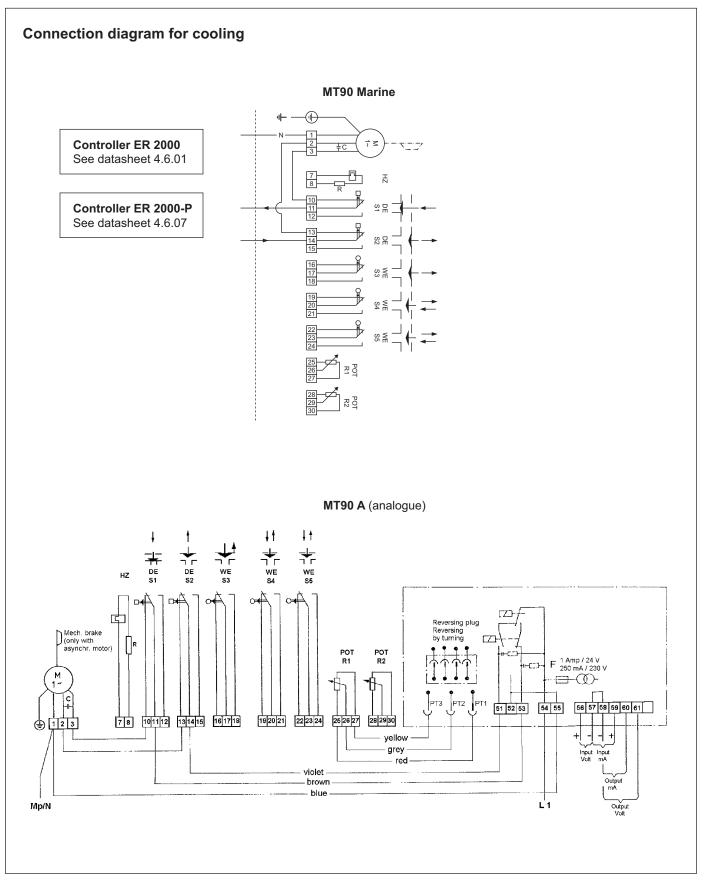
Dimension sketch





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Clorius Controls A/S

Tempovej 27 · DK-2750 Ballerup · Denmark Tel.: +45 77 32 31 30 · Fax: +45 77 32 31 31

E-mail: mail@cloriuscontrols.com Web: www.cloriuscontrols.com